

MAT3

**MATHEMATICAL TRIPOS**      **Part III**

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Monday 9 June 2025    9:00 am to 12:00 pm

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**PAPER 302****SYMMETRIES, FIELDS AND PARTICLES****Before you begin please read these instructions carefully**Candidates have **THREE HOURS** to complete the written examination.Attempt no more than **THREE** questions.There are **FOUR** questions in total.

The questions carry equal weight.

**STATIONERY REQUIREMENTS**Cover sheet  
Treasury tag  
Script paper  
Rough paper**SPECIAL REQUIREMENTS**

None

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| <b>You may not start to read the questions<br/>printed on the subsequent pages until<br/>instructed to do so by the Invigilator.</b> |
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## 1

(a) Define what it means for  $G$  to be a *Lie group*, clearly stating the group axioms in mathematical terms.

(b) Let  $g(x)$ ,  $g(y)$ , and  $g(z)$  be elements of  $G$  depending on coordinates  $x$ ,  $y$ , and  $z \in \mathbb{R}^n$ . Suppose that these group elements are close to the identity in  $G$ , which corresponds to the origin in the coordinate patch used. Assuming  $g(z) = g(y)g(x)$ , discuss how  $z$  can be related to  $x$  and  $y$  and the implications of the group axioms.

(c) Consider the group commutator  $g(w) := g(y)^{-1}g(x)^{-1}g(y)g(x)$ . Relate  $w$  to  $x$  and  $y$  using a Taylor expansion to leading, nonvanishing order.

(d) Consider the set of matrices which have the following form,

$$S := \left\{ \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix} \mid a, b \in \mathbb{R} \right\}.$$

With reference to the group axioms, determine the largest subset of  $S$  that forms a group,  $G$ , under matrix multiplication, specifying clearly any conditions on  $a$  and  $b$  that may be required.

- (i) What is the underlying manifold of  $G$ ? Is it connected or disconnected? Justify your answers.
- (ii) Is the defining representation of the group given above reducible? If so, identify an invariant subspace.
- (iii) Consider the following subgroups of  $G$ ,

$$H_0 = \left\{ \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix} \mid a > 0 \right\}, \quad H_1 = \left\{ \begin{pmatrix} a & 0 \\ 0 & 1 \end{pmatrix} \mid a > 0 \right\}, \quad H_2 = \left\{ \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix} \right\}.$$

For each  $H_n$  above ( $n = 0, 1, 2$ ), explain whether  $H_n$  is normal (justifying your answer) and, if it is, determine the quotient group  $G/H_n$ .

## 2

This question concerns the Poincaré group in Minkowski spacetime with 1 time and 2 space dimensions. Under this group, spacetime coordinates transform as

$$x^\mu \mapsto \Lambda^\mu{}_\nu x^\nu + a^\mu,$$

where  $\mu, \nu \in \{0, 1, 2\}$ , and  $a^\mu$  and  $\Lambda^\mu{}_\nu$  are parameters of such transformations. Take the Minkowski metric signature to be  $(+, -, -)$ .

(a) State the defining condition which a  $3 \times 3$  matrix  $\Lambda$  must satisfy in order to be an element of the Lorentz group in  $1 + 2$  dimensions. Show what this condition implies for the determinant of  $\Lambda$  and the temporal-temporal component of  $\Lambda$ .

(b) Recall that  $SL(2, \mathbb{R})$  is the group of  $2 \times 2$  real matrices with determinant 1. Show that there is a group homomorphism from  $SL(2, \mathbb{R})$  to the proper, orthochronous Lorentz group in  $1 + 2$  dimensions, finding an explicit expression for the map. Is this map an isomorphism?

[Hint: consider the space  $\mathcal{M}$  of real  $2 \times 2$  matrices spanned by  $\{\tau_0, \tau_1, \tau_2\}$ , with

$$\tau_0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad \tau_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad \tau_2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$

Construct a map  $\phi$  from Minkowski space in  $1 + 2$  dimensions to  $\mathcal{M}$  such that  $\phi(x) = X$ , where  $\det X = x^2$ .]

(c) Write the Poincaré group in  $1 + 2$  dimensions as a semidirect product, and give a definition of the subgroups known as *little groups*. [A full derivation is not expected here, but comment on why the semidirect product nature of the group is important.]

(d) Determine the unitary irreducible representations of the Poincaré group suitable for describing states of a single *massive* particle.

(e) Determine the unitary irreducible representations of the Poincaré group suitable for describing states of a single *massless* particle.

## 3

This question concerns the Lie algebra  $\mathfrak{su}(2)$  and its finite-dimensional, irreducible representations. You may find the following identities useful. The Pauli matrices are

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

Given an angle  $\theta$  and a 3-component unit vector  $\mathbf{n}$ ,

$$\exp\left(\frac{i\theta \mathbf{n} \cdot \boldsymbol{\sigma}}{2}\right) = I \cos \frac{\theta}{2} + i \mathbf{n} \cdot \boldsymbol{\sigma} \sin \frac{\theta}{2}.$$

(a) Give a definition for the matrix Lie group  $SU(2)$  and derive conditions determining which  $2 \times 2$  matrices are elements of the Lie algebra  $\mathfrak{su}(2)$ . Determine the structure constants for the basis  $\{T_1, T_2, T_3\}$ , where

$$T_k = -\frac{i}{2} \sigma_k \quad \text{for } k = 1, 2, 3.$$

(b) Using the Cartan–Weyl basis  $H = 2iT_3$ ,  $E_{\pm} = i(T_1 \pm iT_2)$ , construct an eigenvector basis for the finite-dimensional, irreducible representation  $d_{\Lambda}$  whose highest weight is  $\Lambda$ . Hence deduce the dimension of this space in terms of  $\Lambda$ .

(c) Take as given the fact that for some angle  $\theta$  and unit vector  $\mathbf{n}$  the following *disentangling identity* holds:

$$\exp\left(\frac{i\theta \mathbf{n} \cdot \boldsymbol{\sigma}}{2}\right) = e^{i\alpha E_-} \exp\left(\frac{i\beta H}{2}\right) e^{i\gamma E_+}$$

for some  $\alpha$ ,  $\beta$ , and  $\gamma$  which are generally complex. Taking  $\mathbf{n} = (1, 0, 0)$ , determine  $\alpha$ ,  $\gamma$ , and  $\exp(i\beta H/2)$  in terms of  $\theta$ . [Do not attempt to solve for  $\beta$  itself.]

(d) Returning to the irreducible representation  $d_{\Lambda}$  of part (b), let us denote the  $\Lambda$ -eigenvector of  $d_{\Lambda}(H)$  by  $|\Lambda\rangle$ , i.e.  $d_{\Lambda}(H)|\Lambda\rangle = \Lambda|\Lambda\rangle$ . Determine  $\langle\Lambda|e^{-\theta d(T_1)}|\Lambda\rangle$  as a function of  $\theta$ .

(e) For any angle  $\theta$  define a corresponding state vector

$$|\theta\rangle := e^{-\theta d(T_1)} |\Lambda\rangle.$$

Determine the inner product between two such states, i.e.  $\langle\varphi|\theta\rangle$ . [Hint: Consider a disentangling identity similar to the one in part (c).]

4

This question concerns Cartan's classification of simple, complex, finite-dimensional Lie algebras. Consider the following families of algebras of rank  $r$ , each line giving their classification according to Cartan along with the corresponding Dynkin diagram and complexified Lie algebra:

$$\begin{array}{ll}
 A_r : & \bigcirc - \bigcirc - \bigcirc \cdots \bigcirc - \bigcirc \quad \mathfrak{su}(r+1)_{\mathbb{C}} \\
 B_r : & \bigcirc - \bigcirc - \bigcirc \cdots \bigcirc \Rightarrow \bigcirc \quad \mathfrak{so}(2r+1)_{\mathbb{C}} \\
 C_r : & \bigcirc - \bigcirc - \bigcirc \cdots \bigcirc \Leftarrow \bigcirc \quad \mathfrak{sp}(2r)_{\mathbb{C}} \\
 D_r : & \bigcirc - \bigcirc - \bigcirc \cdots \bigcirc \begin{array}{l} \nearrow \bigcirc \\ \searrow \bigcirc \end{array} \quad \mathfrak{so}(2r)_{\mathbb{C}}
 \end{array}$$

The convention is that an arrow points from the longer root to the shorter.

*In this question you may use any general results for simple, complex, finite-dimensional Lie algebras and their representations as long as they are clearly and correctly stated.*

(a) Given that a rank  $r$  Lie algebra  $\mathfrak{g}$  has simple roots  $\{\alpha_{(j)}\}$  with  $j = 1, 2, \dots, r$ , give definitions for the following terms: (i) *Cartan matrix*, (ii) *fundamental weights*, (iii) *Dynkin labels*, (iv) *dominant weight*, (v) *highest weight of a representation*. Additionally, (vi) determine the linear relation between the simple roots and the fundamental weights.

(b) Consider the rank-3 Lie algebras denoted by  $A_3$ ,  $B_3$ , and  $C_3$ . In each case

- (i) write down the corresponding Cartan matrix, assuming the labelling of roots is from left to right in its Dynkin diagram as depicted above;
- (ii) give the ratio  $|\alpha_{(2)}|/|\alpha_{(3)}|$ ;
- (iii) give the angles between each pair of simple roots.

(c) Find all of the weights for the following representations and write down the dimension of each representation:

- (i)  $d_1$ , the  $A_3$  representation whose highest weight has Dynkin labels  $[1, 0, 0]$ ;
- (ii)  $d_2$ , the  $A_3$  representation whose highest weight has Dynkin labels  $[0, 0, 1]$ ;
- (iii)  $d_3$ , the  $B_3$  representation whose highest weight has Dynkin labels  $[0, 0, 1]$ .

(d) Decompose the  $A_3$  representation  $d_1 \otimes d_2$  into irreducible representations of  $A_3$ .

(e) Let us define a map  $P$  on Dynkin labels such that  $P[\lambda^1, \lambda^2, \lambda^3] = [\lambda^2, \lambda^1, \lambda^2 + \lambda^3]$ . Apply this to the weights of the representation  $d_3$  found in (c)(iii) and note any similarities to the weights of  $d_1$  and  $d_2$  found in (c)(i) and (c)(ii). How can you interpret this?

**END OF PAPER**