

**MATHEMATICAL TRIPOS**      **Part III**

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Wednesday, 7 June, 2017   9:00 am to 12:00 pm

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**PAPER 340****TOPICS IN MATHEMATICS OF INFORMATION**

*Attempt no more than **FOUR** questions.*

*There are **FIVE** questions in total.*

*The questions carry equal weight.*

**STATIONERY REQUIREMENTS**

*Cover sheet*

*Treasury Tag*

*Script paper*

**SPECIAL REQUIREMENTS**

*None*

<p><b>You may not start to read the questions printed on the subsequent pages until instructed to do so by the Invigilator.</b></p>
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1

- (a) Give the definition of a *multiresolution analysis* (MRA) for  $L^2(\mathbb{R})$ . Define the low pass filter  $m$  associated with the scaling function  $\varphi$  of this MRA.
- (b) Explain (without proof) how one can construct an orthonormal wavelet from an MRA. Write down a formula for an orthonormal wavelet in terms of the scaling function and the low pass filter of the associated MRA.
- (c) Suppose that the scaling function  $\varphi$  is an element of  $L^1(\mathbb{R}) \cap L^2(\mathbb{R})$ . Show that if the associated wavelet  $\psi$  has  $p$  vanishing moments, then the derivatives of the low pass filter  $m$  satisfy

$$m^{(k)}(\pi) = 0, \quad k = 0, \dots, p-1.$$

State clearly all theorems (without proof) that you use.

- (d) Hence deduce that the derivatives of the Fourier transform of  $\varphi$  satisfy for  $k = 0, \dots, p-1$ ,

$$\hat{\varphi}^{(k)}(2\pi j) = 0, \quad \forall j \in \mathbb{Z} \setminus \{0\}.$$

2

- (a) Let  $\mathcal{B} := \{g_m\}_{m \in \mathbb{N}}$  be an orthonormal basis of a Hilbert space  $\mathcal{H}$ . Given  $f \in \mathcal{H}$ , define its  $N$ -term linear approximation  $f_N^{lin}$  and its  $N$ -term nonlinear approximation  $f_N^{nonlin}$  with respect to  $\mathcal{B}$ .
- (b) For  $\alpha > 0$ , define what it means for a function,  $f$ , to be uniformly Lipschitz- $\alpha$  over  $[0, 1]$ . Define the space  $C^\alpha$  of Hölder- $\alpha$  functions.

In the following, let  $\mathcal{H} = L^2([0, 1])$  and let  $\{\psi_{j,l}\}_{j,l}$  be an orthonormal basis generated by a Daubechies wavelet which is  $q$  times continuously differentiable and has  $q$ -vanishing moments, and adapted to the interval  $[0, 1]$ .

- (c) Given a function  $f \in C^\alpha$  with  $0 < \alpha < q$ , show that  $|\langle f, \psi_{j,n} \rangle| \leq C 2^{-j(\alpha+1/2)} \|f\|_{C^\alpha}$  where the constant  $C > 0$  is independent of  $f$ .
- (d) Suppose that  $f \in L^\infty([0, 1])$  has  $K$  discontinuities and is uniformly Lipschitz- $\alpha$  between these discontinuities, where  $1/2 < \alpha < q$ . Show that the nonlinear approximation error  $\epsilon_n(N, f) := \|f_N^{nonlin} - f\|_{L^2([0,1])}^2$  satisfies

$$\epsilon_n(N, f) = \mathcal{O}(N^{-2\alpha}).$$

You may use without proof the fact that there exists a constant  $C > 0$  such that for all  $g \in L^\infty([0, 1])$ ,

$$|\langle \psi_{j,n}, g \rangle| \leq C 2^{-j/2} \|g\|_{L^\infty([0,1])}.$$

## 3

- (a) Let  $A \in \mathbb{C}^{m \times N}$  and let  $\mathcal{N}(A)$  denote the null space of  $A$ . What does it mean for  $A$  to satisfy the null space property of order  $s$ ? Assuming that  $A$  satisfies the null space property of order  $s$ , show that  $\mathcal{N}(A)$  does not contain any  $2s$ -sparse vector other than the zero vector. Hence deduce that given any  $s$ -sparse vector, which we denote by  $x$ ,  $x$  is the unique solution to

$$\min_{z \in \mathbb{C}^N} \|z\|_0 \text{ subject to } Ax = Az.$$

Let  $y \in \mathbb{C}^m$  and let  $q \in (0, 1]$ . Consider the minimization problem

$$\min_{z \in \mathbb{C}^N} \|z\|_q \text{ subject to } Az = y. \quad (P_q)$$

- (b) Show that any  $s$ -sparse vector  $x$  is the unique minimizer to  $(P_q)$  with  $y = Ax$  if and only if for all  $S \subset \{1, \dots, N\}$  with  $|S| \leq s$ ,

$$\|v_S\|_q^q < \|v_{S^c}\|_q^q, \quad \forall v \in \mathcal{N}(A) \setminus \{0\}.$$

In the above,  $S^c := \{1, \dots, N\} \setminus S$ . You may use the fact that  $(a + b)^q \leq a^q + b^q$  for all  $a, b \geq 0$  and  $q \in (0, 1)$ .

- (c) Show that if any  $s$ -sparse vector  $x$  is the unique minimizer to  $(P_q)$  with  $y = Ax$ , then any  $s$ -sparse vector  $x$  is the unique minimizer to  $(P_p)$  with  $y = Ax$  and  $p \in (0, q)$ .

4

- (a) Let  $\Omega = (0, 1)^2$  and let  $u \in L^1(\Omega)$ . State the definition of the total variation of  $u$  and define the space  $BV(\Omega)$  with the corresponding norm.
- (b) Give an example of a function which is in  $BV(\Omega)$  but not in the Sobolev space  $W^{1,1}(\Omega)$ . Briefly justify your answer (You may state without proof any properties of Sobolev functions that you use).
- (c) Let  $\alpha > 0$ ,  $\Omega = \mathbb{R}^2$  and let  $J : L^2(\Omega) \rightarrow [0, \infty]$  be defined by  $J(u) = |Du|(\Omega)$ , with  $J(u) = +\infty$  if  $u \notin BV(\Omega)$ . Show that  $u$  is the minimizer of

$$\min_{v \in L^2(\Omega)} \left\{ \alpha J(v) + \frac{1}{2} \|v - g\|_{L^2}^2 \right\} \quad (1)$$

if and only if

$$\frac{g - u}{\alpha} \in \partial J(u).$$

- (d) Let  $g(x) = \chi_{B(0,R)}$  be the characteristic function on the ball in  $\mathbb{R}^2$  of radius  $R$ , centred at 0. Derive an explicit formula for the minimizer  $u$  of (1).

5

Let  $X = \mathbb{R}^{N \times N}$  for some  $N \in \mathbb{N}$  and write  $X^2 := X \times X$ . For  $g \in X$ ,  $\lambda > 0$ , consider

$$\min_{u \in X} \left\{ \lambda \|\nabla u\|_{2,1} + \frac{1}{2} \|u - g\|_2^2 \right\}$$

where  $\|q\|_2^2 = \sum_{i,j} q_{i,j}^2$  for  $q \in X$ ,  $\|p\|_{2,1} = \sum_{i,j} \sqrt{(p_{i,j}^1)^2 + (p_{i,j}^2)^2}$  for  $p = (p^1, p^2) \in X^2$ , and  $\nabla : X \rightarrow X^2$  is the discrete gradient operator defined by

$$(\nabla u)_{i,j} = \begin{pmatrix} (D_x^+ u)_{i,j} \\ (D_y^+ u)_{i,j} \end{pmatrix},$$

with

$$(D_x^+ u)_{i,j} = \begin{cases} u_{i+1,j} - u_{i,j} & i < N \\ 0 & i = N, \end{cases} \quad (D_y^+ u)_{i,j} = \begin{cases} u_{i,j+1} - u_{i,j} & j < N \\ 0 & j = N. \end{cases}$$

This question is about the dual formulation of this minimization problem and the use of the projected gradient descent algorithm.

- (a) Find an expression for the minimizer  $u$  as the projection of  $g$  onto a closed convex set. Carefully justify every step of your derivation and quote any definitions and theorems that you use.
- (b) Give an iterative algorithm to compute this projection and state under which conditions the iterates converge.
- (c) Briefly describe the convex set associated with the projection when you consider instead for  $q \geq 1$ , the minimization problem

$$\min_{u \in X} \left\{ \lambda \|Au\|_{q,1} + \frac{1}{2} \|u - g\|_2^2 \right\}$$

where  $A : X \rightarrow X^d$  for  $d \in \mathbb{N}$  is a linear operator and  $\|v\|_{q,1} = \sum_{i,j} \left( (v_{i,j}^1)^q + \dots + (v_{i,j}^d)^q \right)^{1/q}$  for  $v = (v^1, \dots, v^d) \in X^d$ .

**END OF PAPER**