

MATHEMATICAL TRIPOS      Part III

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Tuesday, 7 June, 2016    1:30 pm to 3:30 pm

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PAPER 326

INVERSE PROBLEMS

*Attempt no more than **TWO** questions.*

*There are **THREE** questions in total.*

*The questions carry equal weight.*

**STATIONERY REQUIREMENTS**

*Cover sheet*

*Treasury Tag*

*Script paper*

**SPECIAL REQUIREMENTS**

*None*

<p><b>You may not start to read the questions printed on the subsequent pages until instructed to do so by the Invigilator.</b></p>
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## 1 Generalised inverses and regularisation of linear inverse problems

This question deals with the concepts of generalised inverses and regularisation.

- (i) Recall the definition of the Moore-Penrose inverse.
- (ii) Compute the Moore-Penrose inverse of the right-shift operator  $K : \ell^2 \rightarrow \ell^2$ ,  $\{u_j\}_{j \in \mathbb{N}} \rightarrow \{f_j\}_{j \in \mathbb{N}}$ , with

$$f_j = (Ku)_j := \begin{cases} 0 & j = 1 \\ u_{j-1} & j \geq 2 \end{cases}.$$

It is necessary to also state the domain of  $K^\dagger$ .

- (iii) Let  $\mathcal{U}$  and  $\mathcal{V}$  be Hilbert spaces. What is an equivalent condition to  $f \in \mathcal{R}(K)$  for  $K \in \mathcal{K}(\mathcal{U}, \mathcal{V})$ ?
- (iv) Recall the definition of a regularisation (operator)? Give an example for a regularisation.
- (v) We consider the problem of differentiation, formulated as the inverse problem of finding  $u$  from  $Ku = f$  with the integral operator  $K : L^2([0, 1]) \rightarrow L^2([0, 1])$  defined as

$$(Ku)(y) := \int_0^y u(x) dx.$$

Show that  $R_\alpha : L^2([0, 1]) \rightarrow L^2([0, 1])$  with

$$(R_\alpha f)(x) := \frac{1}{\alpha} \begin{cases} f(x + \alpha) - f(x) & x \in [0, \frac{1-\alpha}{2}[ \\ f(x + \frac{\alpha}{2}) - f(x - \frac{\alpha}{2}) & x \in [\frac{1-\alpha}{2}, \frac{1+\alpha}{2}[ \\ f(x) - f(x - \alpha) & x \in [\frac{1+\alpha}{2}, 1] \end{cases}$$

for  $\alpha \in ]0, 1/2[$  is a convergent regularisation method and determine a corresponding a-priori parameter choice rule. In order to do so, verify the estimate

$$\|K^\dagger f - R_\alpha f^\delta\|_{L^2([0,1])} \leq \frac{\sqrt{6}}{\alpha} \delta + \frac{\sqrt{17}}{4} \alpha c$$

first, for  $f \in H^2([0, 1])$ ,  $\|f''\|_{L^2([0,1])} \leq c$  and  $f^\delta \in L^2([0, 1])$  with  $\|f - f^\delta\|_{L^2([0,1])} \leq \delta$ . Without proof you are allowed to use the estimate

$$\int_0^{\frac{1-\alpha}{2}} |(R_\alpha(f))(x) - f'(x)|^2 dx + \int_{\frac{1+\alpha}{2}}^1 |(R_\alpha(f))(x) - f'(x)|^2 dx \leq \alpha^2 c^2.$$

## 2 Bregman distances and error estimates

This question deals with error estimates of variational regularisation methods in the Bregman distance setting.

- (i) Recall the definitions of the subdifferential for convex functionals and the Bregman as well as the symmetric Bregman distance.
- (ii) Compute the Bregman distance  $D_E(x, y)$  for  $E$  being the maximum-entropy regularisation

$$E(x) := \int_{\Omega} x(t) \log(x(t)) - x(t) dt,$$

for a bounded domain  $\Omega$ . Use without proof that the subdifferential of a Fréchet-differentiable functional consists of its Fréchet-derivative only.

- (iii) Draw a sketch of the Bregman distance  $D_E^p(1, 0)$  for the function  $E(x) := |x|$  and a  $p \notin \{-1, 1\}$  of your choice.
- (iv) Let  $K \in \mathcal{L}(\mathcal{U}, \mathcal{V})$ , and  $J : \mathcal{U} \rightarrow \mathbb{R}$  be a convex, lower semi-continuous and proper functional. Further assume that there exist  $u^\dagger \in \mathcal{U}$  and  $f \in \mathcal{V}$  with  $Ku^\dagger = f$ . Show that the source condition

$$\mathcal{R}(K^*K) \cap \partial J(u^\dagger) \neq \emptyset, \quad (\text{SC})$$

i.e. there exists an element  $v \in \mathcal{U} \setminus \{0\}$  with  $K^*Kv \in \partial J(u^\dagger)$ , is equivalent to the existence of a function  $\bar{u} \in \mathcal{U}$  such that  $u^\dagger$  satisfies

$$u^\dagger \in \arg \min_{u \in \mathcal{U}} \left\{ \frac{1}{2} \|Ku - K\bar{u}\|_{\mathcal{V}}^2 + \alpha J(u) \right\},$$

for  $\alpha > 0$ .

- (v) Let the same assumptions hold true as in the previous exercise, but let  $u^\dagger$  now be a  $J$ -minimising least-squares solution (for given data  $f \in \mathcal{V}$ ). Verify the estimate

$$D_J^w(u_\alpha, u^\dagger) \leq D_J^w(u^\dagger - \alpha v, u^\dagger),$$

for  $u_\alpha$  being a solution of the Tikhonov-type regularisation functional

$$u_\alpha \in \arg \min_{u \in \mathcal{U}} \left\{ \frac{1}{2} \|Ku - f\|_{\mathcal{V}}^2 + \alpha J(u) \right\},$$

and specify  $w$ .

- (vi) How is the source condition (SC) connected to the generalised Eigenvalue problem? What are the consequences for the previously derived error estimate in case  $u^\dagger$  is a generalised Eigenfunction of  $J$  and  $J$  is one-homogeneous? Does the result imply  $u_\alpha = u^\dagger$ ?

### 3 Computational realisation of variational regularisation methods

This question deals with basic concepts in convex analysis and the computational realisation of convex, variational regularisation methods.

- (i) Recall the definition of the proximity, respectively the resolvent operator, for a convex functional  $E$ .
- (ii) Compute the Fréchet-derivative of

$$E(x) = \int_{\Sigma} y(t) \log \left( \frac{y(t)}{(Kx)(t)} \right) + (Kx)(t) - y(t) dt,$$

for  $K \in \mathcal{L}(\text{PDF}(\Omega), L_+^1(\Sigma))$ , bounded domains  $\Omega$  and  $\Sigma$ , and  $y(t) > 0$  for all  $t \in \Sigma$ . Without proof you are allowed to make use of the fact that the Fréchet-derivative  $E'$  satisfies

$$\left. \frac{d}{d\tau} E(x + \tau z) \right|_{\tau=0} = \langle z, E'(x) \rangle = \int_{\Omega} z(t) (E'(x))(t) dt,$$

and that the order of differentiation (with respect to  $\tau$ ) and integration (with respect to  $t$ ) can be interchanged.

- (iii) Compute simple, closed-form solutions of the resolvent operators for the following convex functions or functionals:

- $E(x) = \frac{1}{2} \|DQx - y\|_2^2$ , where  $D \in \mathbb{R}^{m \times n}$  and  $Q \in \mathbb{R}^{n \times n}$  are matrices such that  $D^T D$  is a diagonal matrix, and  $Q$  is an orthogonal matrix.
- $E(x) = \int_{\Omega} y(t) \log \left( \frac{y(t)}{x(t)} \right) + x(t) - y(t) dt$ , for a bounded domain  $\Omega$  and  $y(t) > 0$  for all  $t \in \Omega$ . Which one of the solutions makes sense and which one does not?
- $E(x) = |x|$ .

- (iv) The convex conjugate  $E^* : \mathcal{X}^* \rightarrow \mathbb{R} \cup \{+\infty\}$  of a functional  $E : \mathcal{X} \rightarrow \mathbb{R} \cup \{+\infty\}$  is defined as

$$E^*(y) := \sup_{x \in \mathcal{X}} \langle x, y \rangle - E(x).$$

Compute the convex conjugate  $E^*$  of the function  $E(x) := \frac{\lambda}{2} |x - z|^2$ , for a positive scalar  $\lambda \in \mathbb{R}$ .

- (v) Show that the algorithm

$$\begin{aligned} w^{k+1} &= \left( I + \frac{1}{\tau} \partial F^* \right)^{-1} \left( \frac{1}{\tau} u^k - D^T v^k \right) \\ u^{k+1} &= u^k - \tau \left( D^T v^k + w^{k+1} \right) \\ v^{k+1} &= (I + \sigma \partial G)^{-1} (v^k + \sigma D(u^{k+1} - \tau(D^T v^k + w^{k+1}))) \end{aligned}$$

is equivalent to the primal-dual hybrid gradient method (PDHGM) as introduced in the lecture, for a matrix  $D \in \mathbb{R}^{m \times n}$  and convex functions  $F^* : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$

and  $G : \mathbb{R}^m \rightarrow \mathbb{R} \cup \{+\infty\}$ . Without proof you are allowed to make use of the Moreau-identity

$$x = (I + \alpha \partial E)^{-1}(x) + \alpha \left( I + \frac{1}{\alpha} \partial E^* \right)^{-1} \left( \frac{x}{\alpha} \right).$$

Conclude (from the lecture) how the parameters  $\tau$  and  $\sigma$  have to be chosen in order to guarantee convergence.

**END OF PAPER**