

MATHEMATICAL TRIPOS Part III

Monday, 30 May, 2016 1:30 pm to 4:30 pm

PAPER 115

DIFFERENTIAL GEOMETRY

*Attempt no more than **THREE** questions.*

*There are **FOUR** questions in total.*

The questions carry equal weight.

STATIONERY REQUIREMENTS

Cover sheet

Treasury Tag

Script paper

SPECIAL REQUIREMENTS

None

<p>You may not start to read the questions printed on the subsequent pages until instructed to do so by the Invigilator.</p>

1

If M is a smooth manifold, explain what is meant by a *smooth vector field* on M . For $\alpha : M \rightarrow N$ a diffeomorphism and X a smooth vector field on M , define the vector field α_*X on N . Given two smooth vector fields X, Y on M , define the *Lie bracket* vector field $[X, Y]$ and state the corresponding *Jacobi identity*.

Given a smooth vector field X on M , describe without proof what is meant by a *local flow* $\phi_t : U \rightarrow \phi_t U$ determined by X (existence and uniqueness statements for such flows may be assumed). Define what is meant by a smooth *tensor* on M , and for any such tensor T define the *Lie derivative* $L_X T$. Identify (with proofs) $L_X T$ when $T = f$ is a smooth function and $T = Y$ is a smooth vector field.

If $\alpha : M \rightarrow N$ is a diffeomorphism and X a smooth vector field on M , with ϕ_t a corresponding local flow, show that the vector field α_*X has a corresponding local flow given by $\alpha \circ \phi_t \circ \alpha^{-1}$. If $M = N$, deduce that $\alpha_*X = X$ if and only if α and the local flows ϕ_t determined by X always commute.

2

Define the exterior derivative map d on p -forms on a smooth manifold M , showing that it is well-defined globally under your definition. Define what is meant by the de Rham cohomology groups $H_{DR}^p(M, \mathbf{R})$ of M . Assuming Green's theorem, show that if Δ is a 2-dimensional disc then $H_{DR}^1(\Delta, \mathbf{R}) = 0$. If M is compact of dimension n , state Stokes's theorem without boundary, showing that it defines a linear map $H_{DR}^n(M, \mathbf{R}) \rightarrow \mathbf{R}$.

Now let G denote a Lie group of dimension n . For $g \in G$, we let $L_g : G \rightarrow G$ be given by left-multiplication by g . Show that one can define a non-zero *invariant* n -form ω on G , that is a smooth n -form for which $(L_g)^*\omega = \omega$ for all $g \in G$ (you need not check that the n -form you define is actually smooth). Assume now the fact that for any n -form ω on G , there is an invariant n -form with the same de Rham cohomology class; when G is compact, deduce that $H_{DR}^n(G, \mathbf{R}) = \mathbf{R}$.

Using the results from this question, calculate de Rham cohomology groups $H_{DR}^1(S^2, \mathbf{R})$ and $H_{DR}^3(S^3, \mathbf{R})$.

3

Given a smooth curve $\gamma : [a, b] \rightarrow M$ on a smooth manifold, define what is meant by a *smooth vector field* $V(t)$ *along* γ . Given a Koszul connection ∇ on M , explain carefully the concepts of the *covariant derivative* of $V(t)$ along γ , and $V(t)$ being *parallel* along γ . Given a tangent vector $V_a \in T_{\gamma(a)}M$, show that there exists a unique parallel vector field $V(t)$ along γ with $V(a) = V_a$. Hence deduce the existence of parallel translation maps $\tau_t : T_{\gamma(a)}M \rightarrow T_{\gamma(t)}M$, which are isomorphisms of vector spaces.

Given two Koszul connections ∇ and $\tilde{\nabla}$, show that there is a tensor Δ on M defined by $\Delta(X, Y) = \nabla_X Y - \tilde{\nabla}_X Y$, where X and Y are local vector fields. A smooth curve γ is said to be a *geodesic* with respect to a Koszul connection ∇ if the smooth vector field $\dot{\gamma}(t)$ along γ is parallel. Explain briefly why it is true that a geodesic (together with parametrisation) is locally determined by its initial point and tangent vector. Show that the connections ∇ and $\tilde{\nabla}$ have the same geodesics (with same parametrizations) if and only if $\Delta(v, v) = 0$ for all tangent vectors v .

4

Let M be an embedded smooth submanifold of a smooth manifold N . Explain how a Koszul connection ∇ on N induces a linear connection (which we shall also denote as ∇) on the bundle $TN|_M$, the restriction of TN to M . Suppose $\langle \cdot, \cdot \rangle$ is a Riemannian metric on N , thus inducing a Riemannian metric on M and determining an orthogonal projection map $\pi : TN|_M \rightarrow TM$ of bundles on M . Show that $D = \pi \circ \nabla$ is a Koszul connection on M .

State the defining properties for the Levi-Civita connection on a Riemannian manifold. Suppose now in the above set-up, we take ∇ to be the Levi-Civita connection on N . For local vector fields V, W on M , we set $II(V, W)$ to be the normal component of $\nabla_V W$ with respect to the metric. Assuming the fact that D as defined above (namely where $D_V W$ is the tangential component of $\nabla_V W$) is the Levi-Civita connection on M , show that II induces a symmetric bilinear form on the tangent bundle of M with values in the normal bundle (called the *second fundamental form*). If R denotes the Riemannian curvature tensor on N and \bar{R} the Riemannian curvature tensor on M , for tangent vectors v, w, x, y to M at P , prove that

$$\bar{R}(x, y, v, w) = R(x, y, v, w) + \langle II(v, x), II(w, y) \rangle - \langle II(v, y), II(w, x) \rangle.$$

[You may use the fact that for a connection ∇ on a vector bundle E , with curvature operator denoted by \mathcal{R} , then for any section σ of E ,

$$\mathcal{R}(V, W)(\sigma) = \nabla_V \nabla_W \sigma - \nabla_W \nabla_V \sigma - \nabla_{[V, W]} \sigma. \quad]$$

END OF PAPER