

MATHEMATICAL TRIPOS Part III

Tuesday, 11 June, 2013 1:30 pm to 3:30 pm

PAPER 62

CONVEX OPTIMISATION WITH
APPLICATIONS IN IMAGE PROCESSING

*Attempt no more than **FOUR** questions.*

*There are **FIVE** questions in total.*

The questions carry equal weight.

STATIONERY REQUIREMENTS

Cover sheet

Treasury Tag

Script paper

SPECIAL REQUIREMENTS

None

<p>You may not start to read the questions printed on the subsequent pages until instructed to do so by the Invigilator.</p>

1

- a) Prove that every closed convex set $C \subseteq \mathbb{R}^n$ is the intersection of all closed half-spaces that contain C .
- b) State the central theorem about the Legendre-Fenchel transform and explain the most important steps in the proof leading to the final relation between f^{**} and cl conf . How is the theorem in a) used in the proof?
- c) Find the subdifferential of $f(x) = \max\{a^\top x, b^\top x\}$ for given $a, b \in \mathbb{R}^n$. Carefully explain each step. [*Hint: It may be helpful to rewrite the maximum as a support function.*]

2

- a) Assume $f : \mathbb{R}^n \times \mathbb{R}^m \rightarrow \bar{\mathbb{R}}$ is a given perturbation function. Define the primal and dual objectives φ, ψ , primal and dual problems, and primal and dual marginal functions p, q . State a sufficient condition for strong duality.
- b) The *inf-convolution* $F : \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$ of two functions $h, k : \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$ is pointwise defined as

$$F(z) := \inf_{x \in \mathbb{R}^n} \{k(x) + h(z - x)\}.$$

Assume that h, k are non-negative real-valued, i.e., $h, k : \mathbb{R}^n \rightarrow [0, +\infty)$, proper, lower semi-continuous, and convex.

Show that for every $z \in \mathbb{R}^n$ we can find a perturbation function $f : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$ with marginal function $p(u) = F(z + u)$. Prove that strong duality holds for every $z \in \mathbb{R}^n$.

- c) Compute the dual objective ψ and show that the inf-convolution can be expressed through the conjugates as $F = (k^* + h^*)^*$. How can we practically compute elements of the subdifferential $\partial F(z)$, assuming k^* and h^* are known?

3

- a) State Farkas' Lemma and prove it by defining suitable cones and using the Legendre-Fenchel transform. Explain any theorems that are used.
- b) Consider the following system of inequalities for $x, y \in \mathbb{R}$:

$$x \geq 0, \quad y - x \geq -1, \quad x + y \leq -2.$$

Transform the system into a suitable standard form and use Farkas' Lemma to prove that it does not have a solution.

4

- a) State the definition of forward- and backward-steps $F_{\tau f}$ and $B_{\tau f}$ in terms of set-valued mappings and motivate their definition. Show that the backward step $B_{\tau f}$ is at most single-valued for every proper, lower semi-continuous, convex function f and $\tau > 0$. Carefully explain each step of the proof. In particular, point out where the assumptions on f are used.
- b) Assume that $\tau > 0$ and f is proper, lower semi-continuous, and convex. Show that a backward step $B_{\tau(f^*)}$ on the *conjugate* f^* can be computed using only a single backward step on f . Carefully explain each step.

5

a) Consider the conic problem in standard form,

$$\inf_{x \in \mathbb{R}^n} c^\top x \quad \text{s.t.} \quad Ax - b \succ_K 0, \quad (1)$$

where K is a proper, closed, convex, self-dual cone with associated canonical barrier function F and $A \in \mathbb{R}^{m \times n}$ has full column rank. State the dual problem. Define the primal-dual central path and state a joint characterization of the points on the primal-dual central path. Starting from this characterization, derive the Newton step for tracing the central path.

b) Consider the constrained TV- L^1 problem

$$\min_{u \in \mathbb{R}^n} \sum_{i=1}^n |u_i - f_i| + \lambda \sum_{i=1}^n \sqrt{\left(u^\top g_i^{(1)}\right)^2 + \left(u^\top g_i^{(2)}\right)^2} \quad \text{s.t.} \quad u \in [0, 1]^n,$$

where $f \in \mathbb{R}^n$ discretizes the given image using n points, $\lambda \in (0, \infty)$ is a weighting parameter, and the matrices $G^{(j)} = (g_1^{(j)}, \dots, g_n^{(j)})^\top$, $j = 1, 2$ discretize the directional derivatives of u in x - and y -direction.

Reformulate the problem in standard conic form (1), introducing additional variables as necessary. You do not need to define A, b and c explicitly, it is sufficient to list all constraints in a way that makes the linearity obvious.

To which class of conic problems does the reformulation belong? Find a suitable canonical barrier function for this problem.

END OF PAPER