

MATHEMATICAL TRIPOS      Part III

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Friday 30 May 2003    1.30 to 4.30

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PAPER 14

DIFFERENTIAL GEOMETRY

*Attempt **THREE** questions.*

*There are **six** questions in total.*

*The questions carry equal weight.*

*All the manifolds and related concepts should be assumed to be smooth.*

**You may not start to read the questions  
printed on the subsequent pages until  
instructed to do so by the Invigilator.**

**1** State the transformation law for the tangent vectors at a point  $p$  of a manifold  $M$ . Show that the ‘velocity vector’  $\dot{a}(0)$  of a curve  $a(t)$  on  $M$  with  $\gamma(0) = p$  is a well-defined tangent vector to  $M$ .

Let a Lie group  $G$  be a subgroup and an embedded submanifold of  $GL(n, \mathbb{R})$ , for some  $n$ . Show carefully that if  $\exp(B_1 t)$  and  $\exp(B_2 t)$  are in  $G$  for all  $|t| < \varepsilon$  (where  $\varepsilon > 0$ ) then any linear combination of  $B_1$  and  $B_2$  is the velocity vector of a curve in  $G$  at the identity element  $I$ . Hence identify the tangent space  $T_I G$  with a linear subspace  $\mathfrak{g}$  of  $n \times n$  matrices. Now suppose that the logarithm maps a neighbourhood of  $I$  in  $G$  onto a neighbourhood of zero in  $\mathfrak{g}$ . Prove that  $\mathfrak{g}$  is closed under the Lie bracket: if  $B_1, B_2 \in \mathfrak{g}$  then  $[B_1, B_2] \in \mathfrak{g}$ .

[Standard properties of the logarithm and exponent for matrices may be used without proof, provided these are clearly stated.]

**2** State the defining properties of the exterior derivative. Let  $U$  denote the open unit ball in  $\mathbb{R}^n$ . Using an appropriate vector field and the map  $f(x) \mapsto \int_0^1 t^{k-1} f(tx) dt$ , or otherwise, construct a linear map  $h_k : \Omega^k(U) \rightarrow \Omega^{k-1}(U)$ , such that  $h_{k+1} \circ d + d \circ h_k = \text{id}_{\Omega^k(U)}$ , and prove Poincaré Lemma. Show that if  $\alpha$  is a differential 1-form on  $S^2$  and  $d\alpha = 0$  then  $\alpha = df$  for some function  $f$ .

State the Hodge decomposition theorem and deduce the relation between harmonic differential forms and de Rham cohomology. Show that the space of harmonic differential forms of top degree on a compact connected oriented manifold  $M$  without boundary is one-dimensional.

[You may assume without proof any properties of the Hodge star operator, provided that you state them accurately.]

**3** Let  $E$  be a real vector bundle of rank  $m$  over a base manifold  $B$ . Prove that  $E$  can be given an inner product ‘varying smoothly with the fibres’.

Define what is meant by a  $G$ -structure on  $E$ , where  $G \subset GL(m, \mathbb{R})$  is a Lie group. Show carefully that the existence of an  $O(m)$ -structure on  $E$  is equivalent to the existence of an inner product on  $E$ . Is it true that every rank  $m$  real vector bundle admits an  $SO(m)$ -structure? Justify your answer.

[Existence of a partition of unity may be assumed without proof.]

**4** Write an essay on the concept of a connection on a vector bundle over a manifold. Your essay should contain at least three different points of view on connections and a proof of equivalence of at least two of these. (You are *not* expected to prove the existence of connections.) Standard theorems may be used without proof, but should be clearly stated.

**5** Define geodesic coordinates on a Riemannian manifold  $M$ . Show, stating clearly any preliminary results that you use, that geodesic coordinates exist on a neighbourhood of any point  $p \in M$ . State and prove Gauss' Lemma.

[You may assume without proof that the length of  $\dot{\gamma}(t)$  is constant for any geodesic  $\gamma(t)$ .]

**6** Define the curvature of a Riemannian metric and the corresponding endomorphism of the tangent bundle  $R(X, Y) \in \text{End}(TM)$ , where  $X, Y$  are two vector fields. Prove the formula  $R(X, Y) = D_{[X, Y]} - [D_X, D_Y]$  and deduce the first Bianchi identity  $R(X, Y)Z + R(Y, Z)X + R(Z, X)Y = 0$  for the Riemann curvature. Construct the Riemann curvature tensor  $R_{ij,kl}$  and show that  $-R_{ji,kl} = R_{ij,kl} = -R_{ij,lk}$  and  $R_{ij,kl} = R_{kl,ij}$ .